

### Fluid / solid heat transfers in the metallurgy cooling processes. Constellium approaches and issues

V. Duhoux, GDR TransInter2 Aussois, September 2024



1

# Constellium At A Glance

Constellium is a leader in transforming **Constellium At A Glance**<br> **Constellium** is a leader in transforming<br>
aluminium into advanced solutions, and<br>
in recycling. in recycling.

We manufacture *innovative*, lightweight, mostly for the **packaging, automotive,** and **aerospace** markets.

We are a **public company** listed on the NYSE (NYSE: CSTM).





# Where We Operate



- ▶ Baltimore, MD
- ▶ Plymouth, Michigan, U.S.
- ▶ Bowling Green, Kentucky, U.S.
- 
- Muscle Shoals, Alabama, U.S.
- ▶ Ravenswood, West Virginia, U.S.
- ▶ San Luis Potosí, Mexico
- ▶ Van Buren, Michigan, U.S.
- White, Georgia, U.S.



- ▶ Paris (HQ)
- ▶ Zurich
- ▶ C-TEC, Voreppe, France
- University Technology Center, Brunel University London
- Děčín, Czech Republic
- ▶ Dahenfeld, Neckarsulm, Germany
- Gottmadingen, Germany
- ▶ Issoire, France
- ▶ Levice, Slovakia
- Montreuil-Juigné, France



- ▶ Nuits-Saint-Georges, France
- ▶ Singen, Germany
- Valais, Switzerland
- ▶ Vigo, Spain
- Žilina, Slovakia



- 
- ▶ Nanjing, China
	- 3 Corporate Offices
	- 3 R&D Centers
	- 25 Manufacturing Plants

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**Our Contribution to the Aluminium Value Chain**<br>
transform aluminium into rolled and extruded products and automotive components, partnering with<br>
our customers to develop new and sustainable solutions. We recycle througho Value Chain<br>We transform aluminium into rolled and extruded products and automotive components, partnering with<br>our customers to develop new and sustainable solutions. We recycle throughout the process to achieve<br>full circ our customers to develop new and sustainable solutions. We recycle throughout the process to achieve full circularity of the value chain







Strong and light, and fully recyclable, aluminium is the sustainable material of the future, from soft drinks to cars and planes, and much more.



Major global supplier of sheets for beverage and food cans, wine and spirit closures, aerosols, luxury cosmetics and more



**Leading provider of** and extrusion-based components, for lighter and safer cars



Key partner of aerospace manufacturers providing plates, sheets and extrusion solutions, and a leader in aluminiumlithium technology with

### Packaging Automotive Aerospace Specialties



Airware® defense marketProvider of a wide range of lightweight and highperformance solutions for the transportation and industry markets, and dedicated solutions for the



### Aerospace plate process Many heats-up and cooling down





# Cooling issues during semicontinuous Direct Chill **Casting**



Slab = cast product before rolling Length 3.5 à 9 m Width 1 à 2.5 m Thickness 300 à 700 mm







Thermo-mechanical distortion of the bottom of the slab during <u>start-up</u>: « butt camber » [Ph. Jarry – Translnter 2019]





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# Mold technologies for achieving film boiling cooling **Mold technologies for achieving film boiling cooling<br>during casting start-up**  $_{\text{Ph. Jarry - TransInter 2019}}$ **<br>Numinum industry uses water holes mold<br>Vater holes design should perform : increase Solution of the Chinologies for achieving film boiling cool<br>
pring casting start-up <sub>[Ph. Jarry – Translnter 2019]</sub><br>
inum industry uses water holes mold<br>
r holes design should perform :<br>
w flowrates during start**

- Aluminum industry uses water holes mold
- ▶ Water holes design should perform :
	- › Low flowrates during start-up
		- $\cdot \rightarrow$  Low and constant extracted heat flux.
		- needed
	- › High flowrates for steady state casting
	- › Impact zone length sufficient to minimize vertical thermal gradient
		- Double line of holes
	- › Jets angle should avoid rebounds, otherwise the cooling is not efficient in the streaming zone, especially during film boiling regime.





# **Our ambition – our need:**<br>We need to feed our transient numerical casting models (thermal – the

**Our ambition – our need:**<br>We need to feed our transient numerical casting models (thermal – thermo-mechanical) with<br>HTC boundary conditions so<br>We need to identify HTC laws, especially in film boiling regime. HTC boundary conditions so need to teed our transient numerical casting models (thermal – t<br>  $\lambda$  boundary conditions so<br>
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need to identify HTC laws, especially in film boiling regime.<br>
2 as a function of metal surface temperature<br>
mg into account:<br>
Water flowrate<br>
els angles<br>
Water temperature<br>
Water quality<br>
- Tit

HTC as a function of metal surface temperature

Taking into account:

- Water flowrate
- Jets angles
- Water temperature
- Water quality
	-
	- ,  $CO_3^2$  et  $HCO_3$ <sup>-</sup>)  $-1$



# Experimental set-up at C-TEC quench test bench

Hot Al sample (500°C) is transferred from a furnace to the quench pilot:





# Protocole expérimental

Thermocouples position, embedded in the sample



Front view of the sample in the quench test bench Left view of the sample with TC position



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# Rewetting front descent



Initial



 $+15s$ 



# Low flow rate – Influence of the surface aspect.<br>Oxidized surface due to quench repetition (Left), deoxided by the surface of the surface of the surface of the<br>Experimental condition (Left), deoxided by the surface of the Oxidized surface due to quench repetition (Left), deoxidized (Right)





# Inverse method

# 2D Direct resolution by finite differences, ADI solver  $p(I)(\frac{1}{\partial t} + \nu)$  graa(1)  $) - a$  $\partial T$   $\rightarrow$   $\overrightarrow{a}$   $\over$  $\partial t$  and  $\left(\frac{1}{2}\right)$ **Inverse method**<br>
2D Direct resolution by finite differences, ADI solver<br>  $\rho C_p(T) \left( \frac{\partial T}{\partial t} + \vec{v} \cdot \overline{g \vec{rad}}(T) \right) = div \left( \overline{\lambda} \overline{grad}(T) \right) + \overline{P}$ <br>
2D Inverse by future steps méthod (« horizon glissant » / spécification y finite differences, ADI solver<br>  $\widehat{rad}(T)$  =  $div(\overline{\overline{\lambda}}grad(T)) + P$ <br>
steps méthod (« horizon glissant » / spécific<br>
n d'erreur J :<br>
,  $\varphi_2^{n+1}, ..., \varphi_6^{n+1}) = \sum_{i=j}^{N} \sum_{j=1}^{ntf} (Y_i^{n+j} - T_i^{n+j})^2 + \alpha \sum_{l=2}^{6} (q_l^{n+1} + q_l^{n+1})^2$ ences, ADI solver<br>  $iv(\bar{\lambda}grad(T)) + P$ <br>  $| ($ « horizon glissant » / spécification de fonction)  $|$ <br>  $) = \sum_{i=j}^{N} \sum_{j=1}^{ntf} (Y_i^{n+j} - T_i^{n+j})^2 + \alpha \sum_{l=2}^{6} (\varphi_{l-1}^{n+1} - \varphi_l^{n+1})^2$ <br>
flux cherché au pas de temps n+1 resolution by finite differences, ADI solver<br>  $T\left(\frac{\partial T}{\partial t} + \vec{v}.\overline{grad}(T)\right) = div\left(\overline{\lambda}\overline{grad}(T)\right) + P$ <br>
e by future steps méthod (« horizon glissant »<br>
a de la fonction d'erreur J :<br>  $J(\varphi_1^{n+1}, \varphi_2^{n+1}, ..., \varphi_6^{n+1}) = \sum_{i=1}^$ ect resolution by finite differences, ADI solver<br>  $\int_{\mathcal{D}}^{r}(T)\left(\frac{\partial r}{\partial t} + \vec{v}.\overline{grad}(T)\right) = div\left(\overline{\lambda}grad}(T)\right) + \lambda$ <br>
erse by future steps méthod (« horizon glissa<br>
tion de la fonction d'erreur J :<br>  $J(\varphi_1^{n+1}, \varphi_2^{n+1}, ..., \varphi$ ect resolution by finite differences, ADI solver<br>  $\int_{r}^{T}(T)\left(\frac{\partial T}{\partial t} + \vec{v}.\overline{grad}(T)\right) = div\left(\overline{\lambda}grad}(T)\right) + P$ <br>
erse by future steps méthod (« horizon glissant » /<br>
tion de la fonction d'erreur J :<br>  $J(\varphi_1^{n+1}, \varphi_2^{n+1}, ..., \var$

olver<br>
)) +  $P$ <br>
glissant » / spécification de fonction) [1]<br>  $\frac{n+j}{i} - T_i^{n+j} - \alpha \sum_{l=2}^{6} (\varphi_{l-1}^{n+1} - \varphi_{l}^{n+1})^2$ <br>
u pas de temps n+1 DI solver<br>  $\overrightarrow{td}(T) + P$ <br>
zon glissant » / spécification de fonction) [1]<br>  $\lim_{t \to 1} (Y_t^{n+t} - T_t^{n+t})^2 + \alpha \sum_{l=2}^6 (\varphi_{l-1}^{n+1} - \varphi_l^{n+1})^2$ <br>
hé au pas de temps n+1 ation de fonction) [1]<br> $\frac{n+1}{l-1} - \varphi^{n+1}_l$ <sup>2</sup>

Minimisation de la fonction d'erreur J :

$$
J(\varphi_1^{n+1}, \varphi_2^{n+1}, ..., \varphi_6^{n+1}) = \sum_{i=j}^N \sum_{j=1}^{ntf} (Y_i^{n+j} - T_i^{n+j})^2 + \alpha \sum_{l=2}^6 (\varphi_{l-1}^{n+1} - \varphi_l^{n+1})^2
$$

- Avec :  $\varphi_1^{n+1}, \varphi_2^{n+1}, ..., \varphi_6^{n+1}$  : valeur du  $n+1,\; \ldots,\; \pmb{\varphi}_6^{n+1}$  : valeur du flux cherché au pas de temps n+1
	-
	-
	- $Y_i^{n+j}$  : température mesurée par le capteur i au pas de temps n+j
	- $T_i^{n+j}$  : température calculée par le modèle direct à la position du capteur i au pas de temps n+j
	- $-\alpha$ : coefficient de régularisation spatiale permettant de pondérer l'écart entre deux flux voisins

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[1] Techniques de l'Ingénieur BE 8.265, 2008, M. Raynaud

# Our need (casting and quenching applications)

- **Our need (casting and quenching applications)**<br>
Improve our ability to determine our cooling HTC laws with/w.o streaming, with a reduced confidence interval.<br>
Interia : be able to discriminate the effect of water quality reduced confidence interval.
- ▶ Criteria : be able to discriminate the effect of water quality and metal surface aspect on HTC curves.
- Understand what are the physical and chemical levers at stake in the relationship between:
	- › Water quality and extracted heat flux
	- › Structure / shape / rugosity of the metal surface, and extracted heat flux
- Interaction of sprays (array of nozzles)?

